
AMENDMENTS TO THE SPECIFICATION

Please amend the specification as is shown below.

Please amend the paragraph beginning on page 12, line 17, and continuing on page 18, with the following amended paragraph.

The magnetism sensing element 12 is composed of a hall element or the like that is made ON by magnetism when the shift lever 1 is inclined onto the first line I as shown in Fig. 5 and so the magnet 11 provided on the [holer] holder 3 comes close to the element. The magnetism sensing element 12 comprises three elements, that is, a magnetism sensing element 12a for detecting that the shift lever 1 is in the neutral position in the manual mode, a magnetism sensing element 12b for detecting that the shift lever is in the shift-up position +, and a magnetism sensing element 12c for detecting that the shift lever is in the shift-down position -. The respective magnetism sensing elements 12a, 12b, 12c are arranged in an arc corresponding to a movement locus of the magnet 11 so as to be capable of detecting approach of the magnet 11 swinging together with the shift lever 1 when the shift lever 1 is swingingly manipulated to the shift-up position + and the shift-down position - from the neutral position in the manual mode as shown in Figs. 1 and 4.

Please amend the paragraph beginning on page 14, line 13, with the following amended paragraph.

That is, when movement is prevented by the stopper 23b, the lock pin 17 abuts against the side abutting surface 3h, merging with an angled lower surface 3i, of the lower portion 3c of the holder 3 to prevent the shift lever 1 present in the second line II on the first path 6b as shown in Fig. 2 from being manipulated to other ranges through the second path 6c, and the shift lever 1 present in the N range of the second line II from being manipulated to the R range of the third line III.